



# MARINE TORSIONMETER





## **INTRODUCTION**

The BOB Lab Marine Torsionmeter System provides an accurate tool to access and monitor the performance and efficiency of the ships shafting.

The transducer accurately measures the on-shaft torque (Nm), shaft rotation speed (rpm) and the transmitted power (kW). The information can also be directly interfaced to ship management systems.

Condition monitoring of a system of this type is important to any modern day vessel. Being able to accurately measure and record the ships static and dynamic torque, the ships power and speed data can help towards determine equipment condition and efficiency. It's a pro-active measure with specific purpose of improving performance and efficiency through a ship shafting system.





## OVERVIEW

### **Overall system highlights:**

- modular, flexible and customizable measuring system
- suitable for sea trials and permanent installations
- easy installation, suitable for all shaft sizes
- high-precision torque and rotational speed measurements
- high-accuracy torque measurement due to digital data transmission (no signal degradation in data transmission paths between sensor and control module)
- on-shaft digital signal processing (torque averaging and peak AC calculation)
- two torque measuring modes:
  - o averaged – on-shaft processed and averaged DC and peak AC (for robust operation in permanent installations)
  - o dynamical – torque waveform transmission (for sea trials) (optional)
- suitable for single / dual shaft systems
- programmable analog (4 – 20 mA,  $\pm 10V$ ) and digital (RS – 232, RS – 485) signal outputs

### **Primary measuring quantities:**

- torque, power, rotational speed (averaged)
- shaft direction indication (ahead / astern)
- support for torque bidirectional measurements

### **Optional measuring quantities:**

- torque, power, rotational speed (dynamical)
- AC torque component peak amplitude,
- AC torque component peak amplitude / DC torque ratio
- programmable alarm states indication
- running hours, energy, fuel consumption, efficiency

### **User interface:**

- 7-segment LED, foil keyboard (basic version)
- touch screen programmable color LCD graphics display 320 x 240 (optional)

### **PC data logging (optional) (for sea trials only):**

- dynamical torque, power and rotational speed log
- FFT analysis





## BLOCK DIAGRAMS

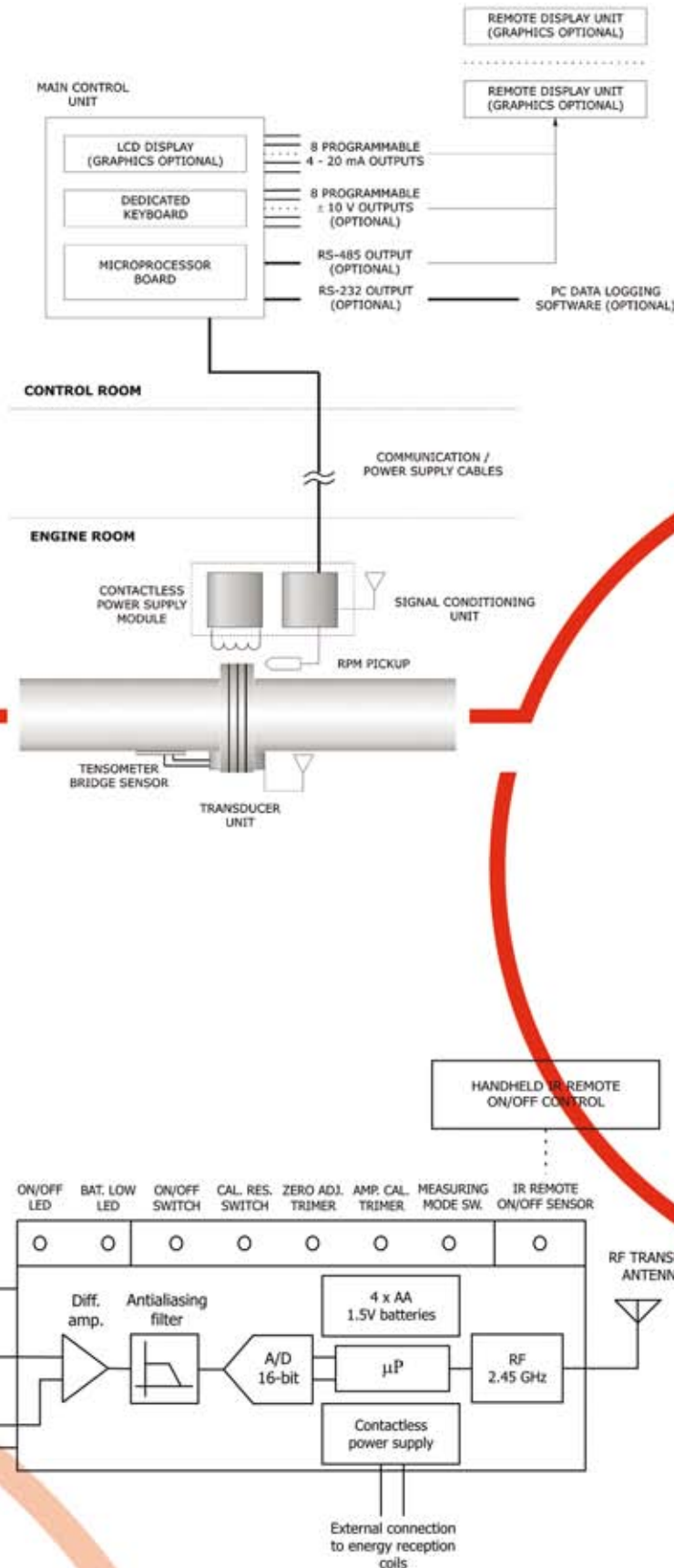


Fig 1. System block diagram

Fig 2: Transducer unit

## BLOCK DIAGRAMS

Fig 3: Contactless power supply module and RF receiver / signal conditioning unit

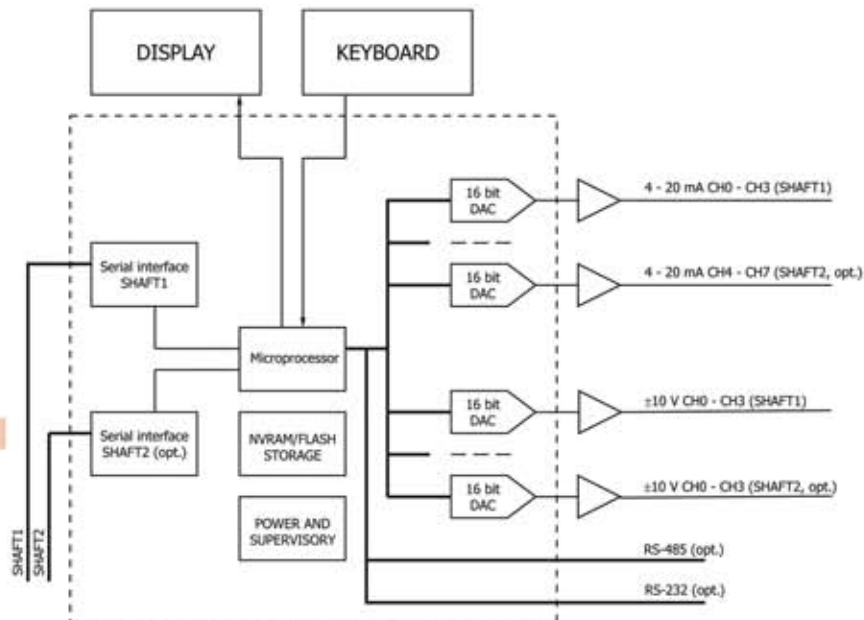
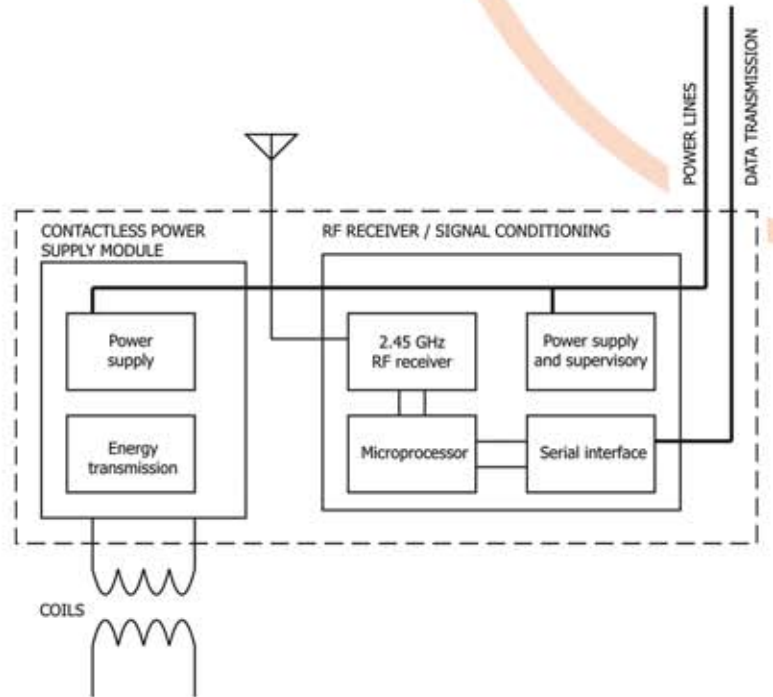


Fig 4: Main control unit



## TECHNICAL SPECIFICATIONS

### **Torque**

- Range > flexible
- Resolution > 4.5 digits

### **Rotational speed**

- Range > 0.01 - 10,000 rpm
- Resolution > 1 ms

### **Overall system accuracy**

- Torque >  $\pm 0.5\%$  F.S.
- RPM >  $\pm 0.1\%$  F.S.
- Power >  $\pm 0.5\%$  F.S.

### **Linearity**

- Torque >  $\pm 0.1\%$  F.S.
- RPM >  $\pm 0.1\%$  F.S.
- Power >  $\pm 0.1\%$  F.S.

### **Torque measuring modes**

- > DC torque, AC torque peak, AC/DC ratio
- Averaged Time intervals > 1 s, 5 s, 10 s, 25 s
- Dynamical (optional) > torque waveform DC – 600 Hz (-3 dB)

### **Input chain freq. response**

- (- 3dB) [Hz] > 0 – 600

### **ADC resolution**

- bits > 16 bit
- full scale resolution > 15 ppm

### **Zero adjustment span**

- (torque measurements) > 0 – 50 % full scale

### **Amp. gain span**

- (torque measurements) > 100 - 3000

### **Analog outputs**

- 4 – 20 mA > 8 outputs, programmable

- $\pm 10$  V (opt.) > 8 outputs, programmable

- RS - 485 (opt.) > proprietary protocol

- RS - 232 (opt.) > proprietary protocol

- Shaft sizes** > suitable for all shaft sizes

- Wireless torque** > 433 MHz ISM license-free band

- transmission** > 128 kbps

- RF transmission power** > 6 - 10 dBm

- Temperature range** > - 10 to 65 °C





## ***Universal Transducer / RF Transmitter Module (for permanent installation and sea trials)***

<b><i>Torque sensor</i></b>	
strain gage range	> 120 $\Omega$ - 1000 $\Omega$
<b><i>RPM sensor</i></b>	> magnetic proximity sensor
<b><i>Power supply</i></b>	
contactless power supply module	> 50 VA
energy transmission	> coupled coils
enclosure	> IP 65
batteries (ortable version)	> 4 x AA 1.5 V
<b><i>Calibration resistance</i></b>	> 200 k $\Omega$
<b><i>Zero adjustment span</i></b>	> 0 – 50 % F.S.
<b><i>Gain adjustment span</i></b>	> 11 – 3000
<b><i>Temperature zero drift</i></b>	> 15 ppm/ $^{\circ}$ C (0.0015 %/ $^{\circ}$ C)
<b><i>Temperature gain drift</i></b>	> 10 ppm/ $^{\circ}$ C (0.0010 %/ $^{\circ}$ C)
<b><i>A/D resolution</i></b>	> 16 bit
<b><i>Sampling frequency</i></b>	> 1500 Hz
<b><i>Analog bandwidth</i></b> (- 3 dB)	> 0 - 600 Hz
<b><i>Input chain linearity</i></b>	> 0.1 %
<b><i>RF transmission frequency</i></b>	> 433 MHz
<b><i>Signal to noise ratio</i></b>	> 60 dB
<b><i>RF transmission output power</i></b>	> 6 dBm
<b><i>Consumption</i></b>	> 25 mA (without sensor)
<b><i>Battery life</i></b> (600 W gage)	> > 24 h
<b><i>Enclosure</i></b>	> IP 65, drip proof
<b><i>Indications</i></b>	> ON/OFF, LED > BAT. LOW, LED
<b><i>Adjustments</i></b>	> ON/OFF, switch > ZERO ADJ., trimmer > GAIN ADJ., trimmer > CAL ADJ., switch > MEAS. MODE., switch
<b><i>Remote control</i></b>	> IC remote ON/OFF control (for extending battery life in ad hoc sea trials installation)

**Notes:** Universal transducer/transmitter module can be mounted as standalone unit (in battery powered mode, for sea trials) or with contactless power supply (for permanent installation). In sea trial installations RF receiver may be located in a range of few meters (depending on room configuration and nearby metal objects arrangement).



## Control module

### Inputs

from SHAFT1, SHAFT2  
torque, power, rotational speed

> proprietary serial protocol (digital values)

### Outputs

4 – 20 mA

> 8, programmable  
> signal modes: averaged, dynamical (opt.)

± 10 V (opt)

> 8, programmable  
> signal modes: averaged, dynamical (opt.)

RS – 485 (opt)

> proprietary protocol

RS – 232 (opt)

> signal modes: averaged, dynamical (opt.)  
> proprietary protocol

### Embedded software modules

> signal modes: averaged, dynamical (opt.)  
> proprietary protocol

### Display

> measuring quantities monitoring

### Display quantities

> measuring system calibration

> shaft constants entry

> quantities monitoring configuration

> analog/digital outputs programming

> single/dual shaft mode selection

> 7 segment indicator (basic version)

> Graphics LCD display 320 x 240 (opt.)

> torque, power, rotational speed

> AC peak, AC/DC ratio (optional)

> programmable alarms (optional)

> working hours, energy, fuel consumption,

> efficiency (opt.)

### Keyboard

> foil, dedicated (basic version)

> touch screen (optional)

### Power supply

> 110 – 220 V, 50 – 60 Hz

### Surge protection

> power supply unit

> input/output stages isolation







Aleja pomoraca 13, HR-10020 ZAGREB  
Tel.: +385 98 319 737, Fax: +385 1 655 4669  
E-mail: boblab@inet.hr  
www.boblab.hr

## Remote displays

Version: **basic** (single/dual shaft)

<b>Display type</b>	>	7 – segment display
<b>Signal inputs</b>		
analog (single/dual)	>	4 / 8 inputs 4 – 20 mA
digital (single/dual)	>	RS – 485
<b>Display quantities</b>	>	torque, power, rotational speed,
	>	AC/DC ratio (optional)
	>	programmable alarms (optional)
<b>Keyboard</b>	>	dedicated foil

Version: **advanced** (single/dual shaft)

<b>Display type</b>	>	touch screen graphics LCD, 320 x 240, color
<b>Signal inputs</b>		
analog (single/dual)	>	4 / 8 inputs 4 – 20 mA
digital (single/dual)	>	RS – 485
<b>Display quantities</b>	>	torque, power, rotational speed
	>	AC peak, AC/DC ratio (optional)
	>	programmable alarms (optional)
	>	working hours, energy, fuel consumption,
	>	efficiency (opt.)
<b>Keyboard</b>	>	touch screen

### Contact:

BOB Lab d.o.o.  
Vibration & Acoustics Consulting

Prof.dr.sc. Nenad Bobanac, dipl.ing.  
Director

Aleja pomoraca 13  
HR-10020 ZAGREB

Tel.: +385 98 319 737  
Fax: +385 1 655 4669  
E-mail: boblab@inet.hr  
www.boblab.hr

